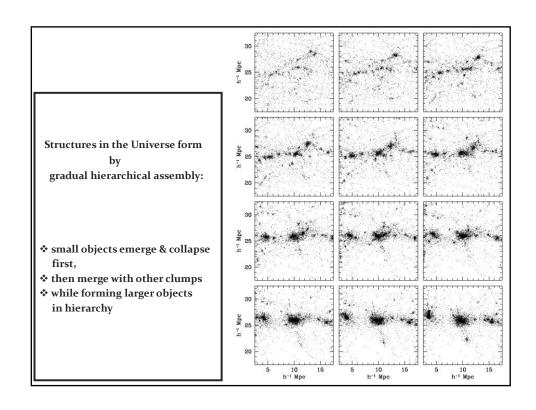
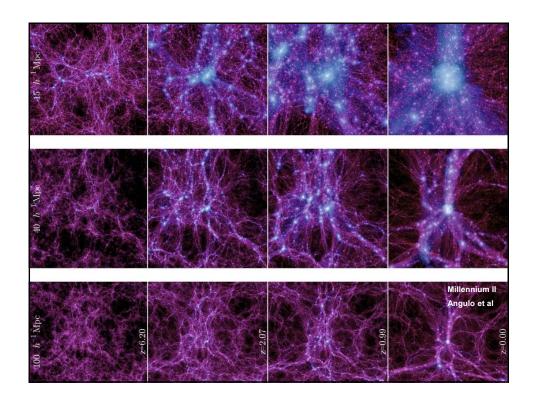
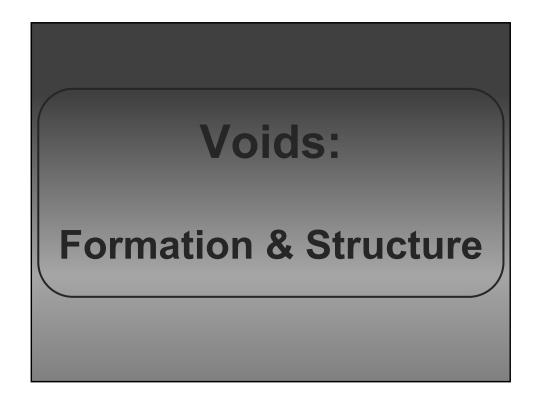


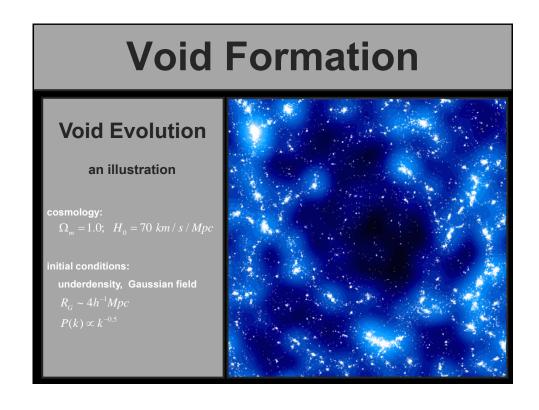
Dynamical Evolution Cosmic Web

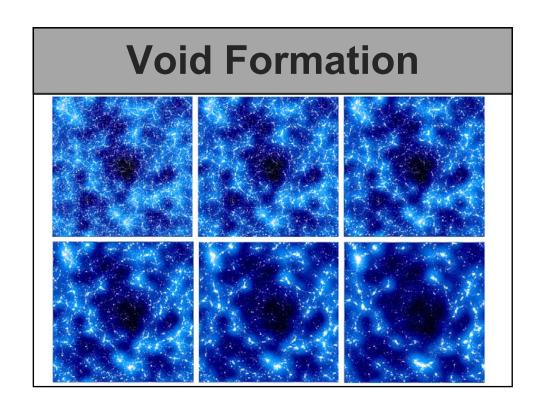
- hierarchical structure formation
- anisotropic collapse
- void formation:
 asymmetry
 overdense vs. underdense





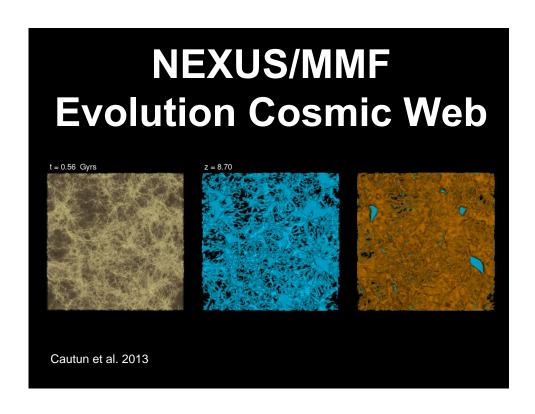


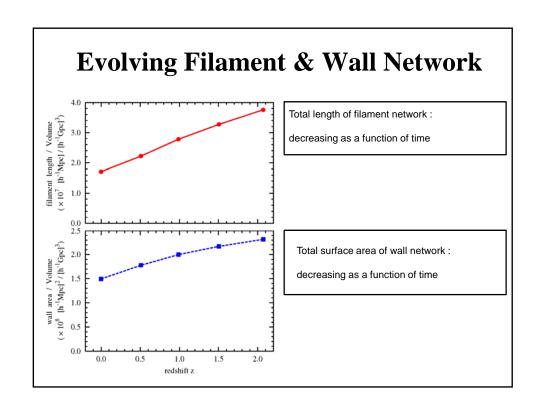


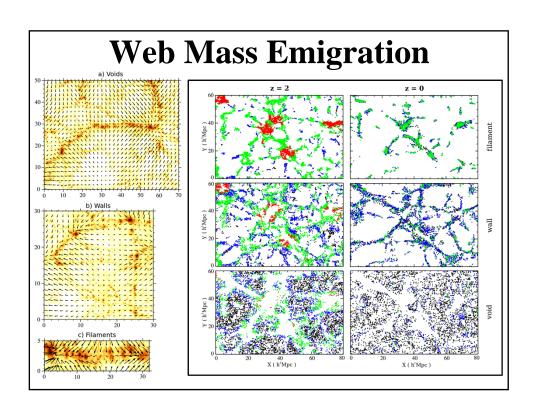


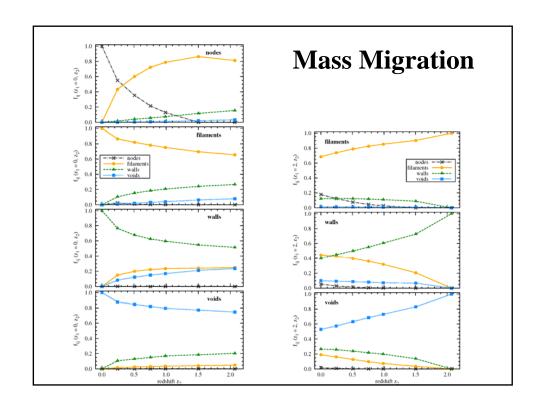
Multiscale Cosmic Web:

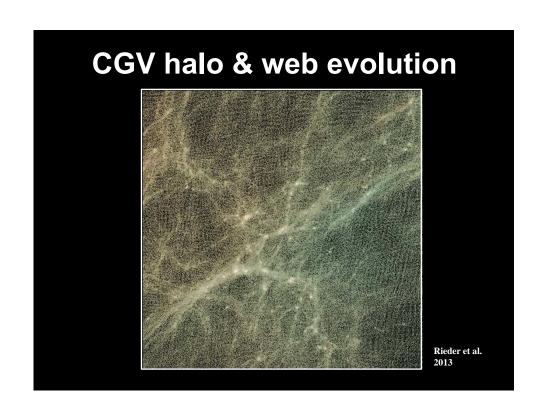
hierarchical evolution

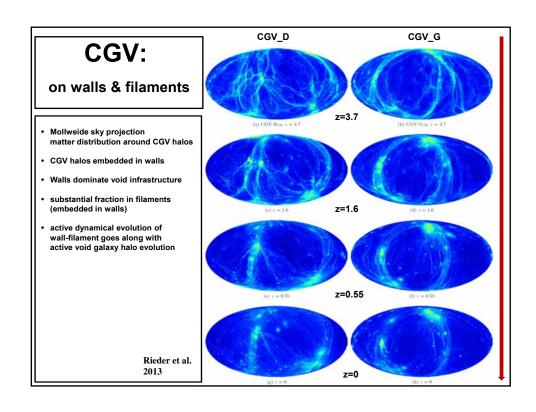


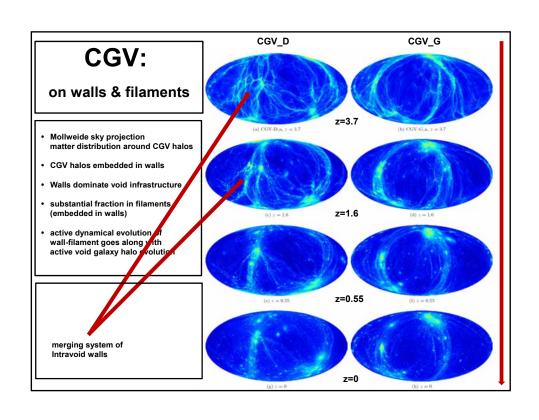


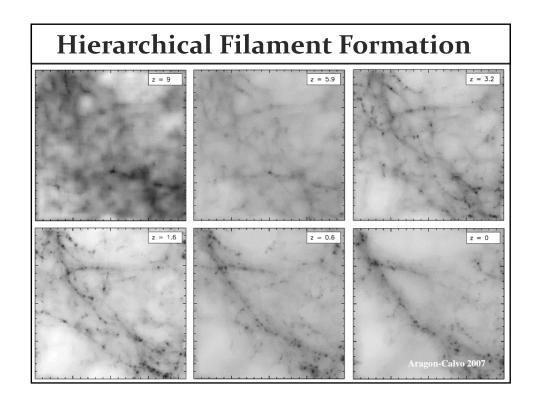


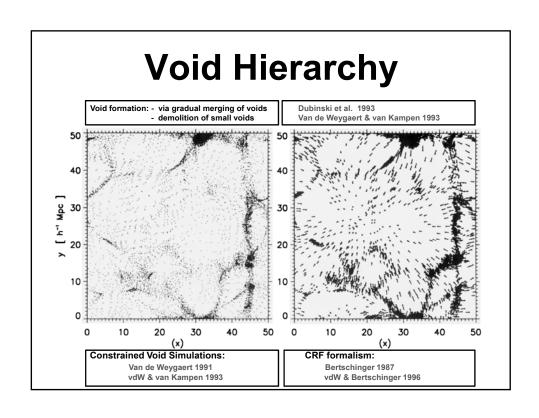


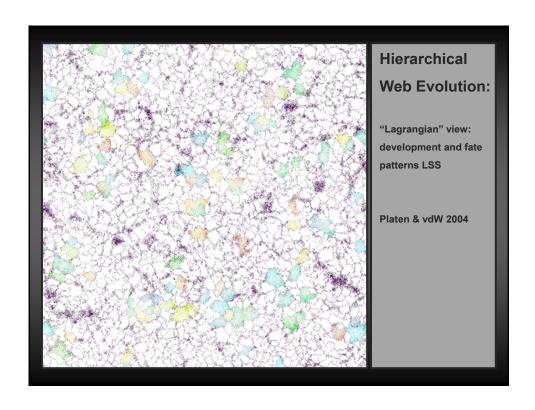


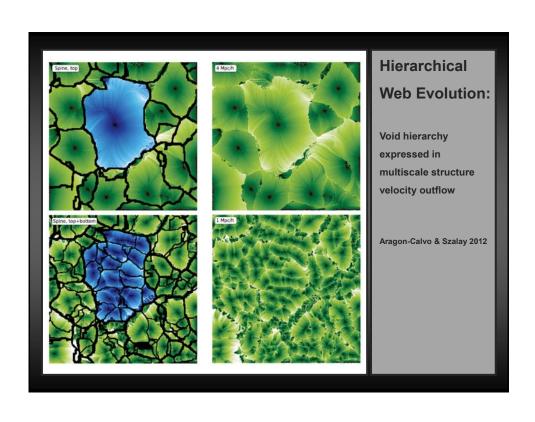








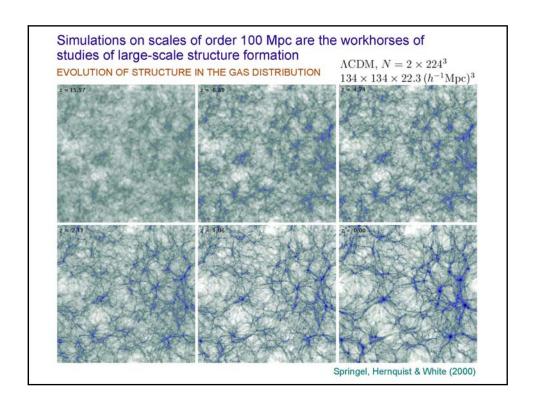


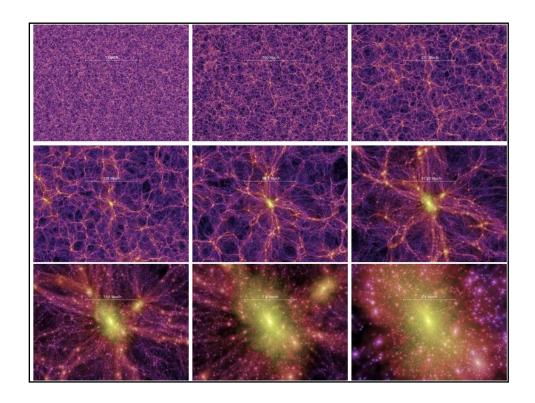


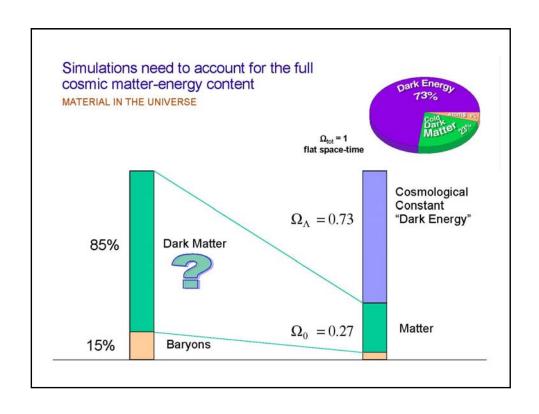
Nonlinear Structure Formation

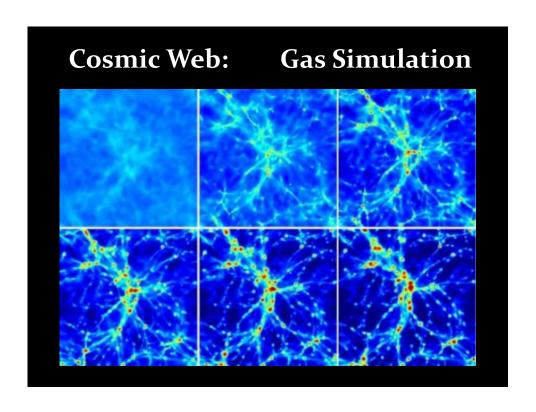
Nbody Simulations

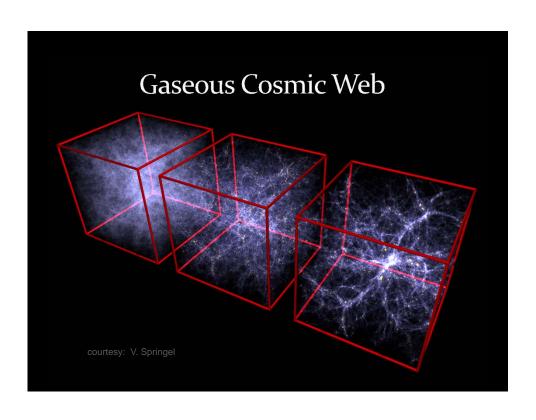
largely based on excellent Potsdam lectures on Nbody simulations (2006) by V. Springel

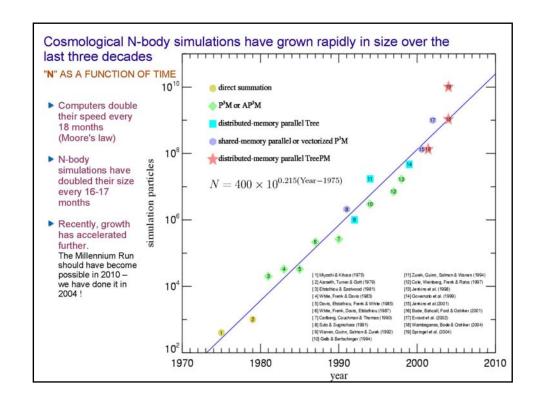












Nbody Dynamics: Fundamentals

We assume that the only appreciable interaction of dark matter particles is **gravity**

COLLISIONLESS DYNAMICS

Because there are so many dark matter particles, it's best to describe the system in terms of the single particle distribution function

$$f = f(\mathbf{x}, \mathbf{v}, t)$$

There are so many dark matter particles that they do not scatter locally on each other, they just respond to their collective gravitational field

Collisionless Boltzmann equation

Poisson-Vlasov System

$$\frac{\mathrm{d}f}{\mathrm{d}t} = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial \mathbf{x}} \cdot \mathbf{v} + \frac{\partial f}{\partial \mathbf{v}} \cdot \left(-\frac{\partial \Phi}{\partial \mathbf{x}} \right) = 0$$
$$\nabla^2 \Phi(\mathbf{x}, t) = 4\pi G \int f(\mathbf{x}, \mathbf{v}, t) \, \mathrm{d}\mathbf{v}$$

Phase-space is conserved along each characteristic (i.e. particle orbit).

The number of stars in galaxies is so large that the two-body relexation time by far exceeds the Hubble time. Stars in galaxies are therefore also described by the above system.

This system of partial differential equations is very difficult (impossible) to solve directly in non-trivial cases.

The N-body method uses a finite set of particles to sample the underlying distribution function

"MONTE-CARLO" APPROACH TO COLLISIONLESS DYNAMICS

We discretize in terms of N particles, which approximately move along characteristics of the underlying system.

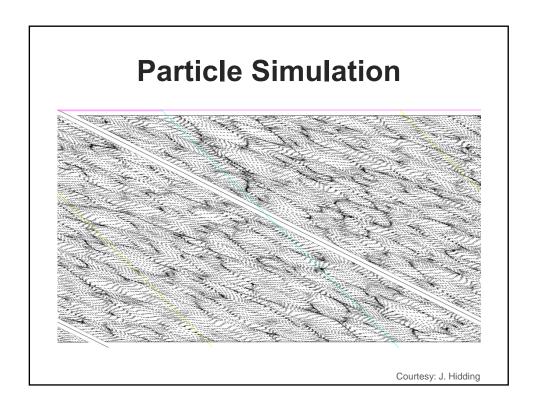
$$\ddot{\mathbf{x}}_i = -\nabla_i \, \Phi(\mathbf{x}_i)$$

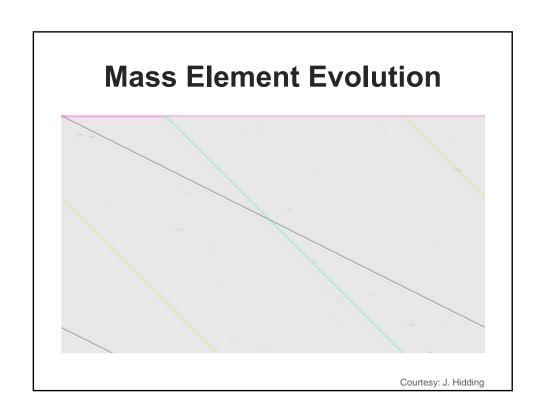
$$\Phi(\mathbf{x}) = -G \sum_{j=1}^N \frac{m_j}{[(\mathbf{x} - \mathbf{x}_j)^2 + \epsilon^2]}$$

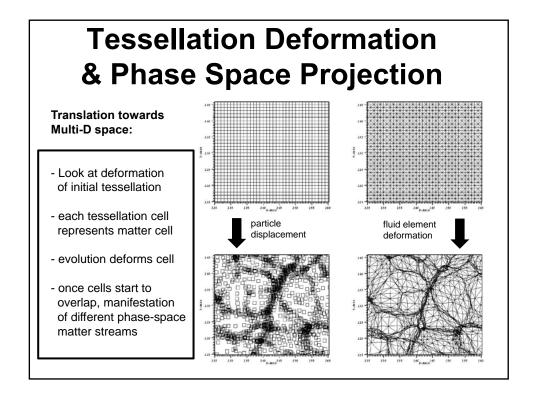
The need for gravitational softening:

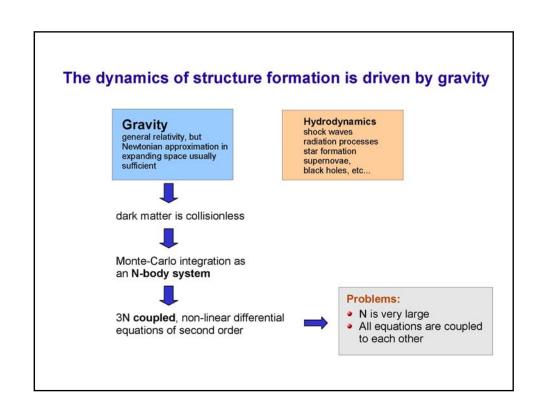
- Prevent large-angle particle scatterings and the formation of bound particle pairs.
- Ensure that the two-body relexation time is sufficiently large.
- Allows the system to be integrated with low-order intergations schemes.

Needed for faithful collisionless behaviour









Two conflicting requirements complicate the study of **hierarchical** structure formation

DYNAMIC RANGE PROBLEM FACED BY COSMOLOGICAL SIMULATIONS

Want small particle mass to resolve internal structure of halos

Want large volume to obtain respresentative sample of universe



Problems due to a small box size:

- Fundamental mode goes non-linear soon after the first halos form. Simulation cannot be meaningfully continued beyond this point.
- No rare objects (the first halo, rich galaxy clusters, etc.)

Problems due to a large particle mass:

- · Physics cannot be resolved.
- Small galaxies are missed.

At any given time, halos exist on a large range of mass-scales!

Several questions come up when we try to use the N-body approach for cosmological simulations

- How do we compute the gravitational forces efficiently and accurately?
- How do we integrate the orbital equations in time?
- How do we generate appropriate initial conditions?

$$egin{aligned} \ddot{\mathbf{x}}_i &= -
abla_i \, \Phi(\mathbf{x}_i) \ \Phi(\mathbf{x}) &= - G \sum_{j=1}^N rac{m_j}{[(\mathbf{x} - \mathbf{x}_j)^2 + \epsilon^2]} \end{aligned}$$

Note: The naïve computation of the forces is an N^2 - task.

Time Integration Issues

Time integration methods

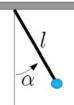
Want to numerically integrate an ordinary differential equation (ODE)

$$\dot{\mathbf{y}} = f(\mathbf{y})$$

Note: y can be a vector

Example: Simple pendulum

$$\ddot{\alpha} = -\frac{g}{l} \sin \alpha$$



$$y_0 \equiv \alpha \quad y_1 \equiv \dot{\alpha}$$

$$\mathbf{\dot{y}} = f(y) = \begin{pmatrix} y_1 \\ -\frac{g}{l} \sin y_0 \end{pmatrix}$$

A numerical approximation to the ODE is a set of values $\{y_0,y_1,y_2,\ldots\}$ at times $\{t_0,t_1,t_2,\ldots\}$

There are many different ways for obtaining this.

Explicit Euler method

$$y_{n+1} = y_n + f(y_n)\Delta t$$

- · Simplest of all
- · Right hand-side depends only on things already non, explicit method
- The error in a single step is $O(\Delta t^2)$, but for the N steps needed for a finite time interval, the total error scales as $O(\Delta t)$!
- · Never use this method, it's only first order accurate.

Implicit Euler method

$$y_{n+1} = y_n + f(y_{n+1})\Delta t$$

- · Excellent stability properties
- · Suitable for very stiff ODE
- Requires implicit solver for y_{n+1}

Implicit mid-point rule

$$y_{n+1} = y_n + f\left(\frac{y_n + y_{n+1}}{2}\right) \Delta t$$

- · 2nd order accurate
- · Time-symmetric, in fact symplectic
- · But still implicit...

Runge-Kutta methods

whole class of integration methods

2nd order accurate

$$k_1 = f(y_n)$$

$$k_2 = f(y_n + k_1 \Delta t)$$

$$y_{n+1} = y_n + \left(\frac{k_1 + k_2}{2}\right) \Delta t$$

4th order accurate.

$$\begin{array}{lll} \textbf{2}^{\text{nd}} \ \text{order accurate} & k_1 & = & f(y_n, t_n) \\ k_1 & = & f(y_n) & k_2 & = & f(y_n + k_1 \Delta t) \\ k_2 & = & f(y_n + k_1 \Delta t) & k_3 & = & f(y_n + k_2 \Delta t/2, t_n + \Delta t/2) \\ y_{n+1} & = & y_n + \left(\frac{k_1 + k_2}{2}\right) \Delta t & y_{n+1} & = & y_n + \left(\frac{k_1}{6} + \frac{k_2}{3} + \frac{k_3}{3} + \frac{k_4}{6}\right) \Delta t \end{array}$$

The Leapfrog

For a second order ODE: $\ddot{\mathbf{x}} = f(\mathbf{x})$

"Drift-Kick-Drift" version

"Kick-Drift-Kick" version

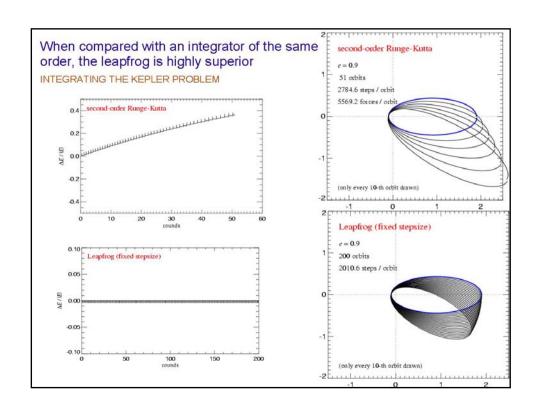
$$x_{n+\frac{1}{2}} = x_n + v_n \frac{\Delta t}{2}$$

$$v_{n+1} = v_n + f(x_{n+\frac{1}{2}}) \Delta t$$

$$x_{n+1} = x_{n+\frac{1}{2}} + v_{n+1} \frac{\Delta t}{2}$$

$$\begin{vmatrix}
x_{n+\frac{1}{2}} &=& x_n + v_n \frac{\Delta t}{2} \\
v_{n+1} &=& v_n + f(x_{n+\frac{1}{2}}) \Delta t \\
x_{n+1} &=& x_{n+\frac{1}{2}} + v_{n+1} \frac{\Delta t}{2}
\end{vmatrix}
\begin{vmatrix}
v_{n+\frac{1}{2}} &=& v_n + f(x_n) \frac{\Delta t}{2} \\
x_{n+1} &=& x_n + v_{n+\frac{1}{2}} \frac{\Delta t}{2} \\
v_{n+1} &=& v_{n+\frac{1}{2}} + f(x_{n+1}) \frac{\Delta t}{2}
\end{vmatrix}$$

- · 2nd order accurate
- symplectic
- · can be rewritten into time-centred formulation



Nbody Dynamics:

Historical

THE ASTROPHYSICAL JOURNAL

AN INTERNATIONAL REVIEW OF SPECTROSCOPY AND ASTRONOMICAL PHYSICS

VOLUME 94

NOVEMBER 1941

NUMBER 3

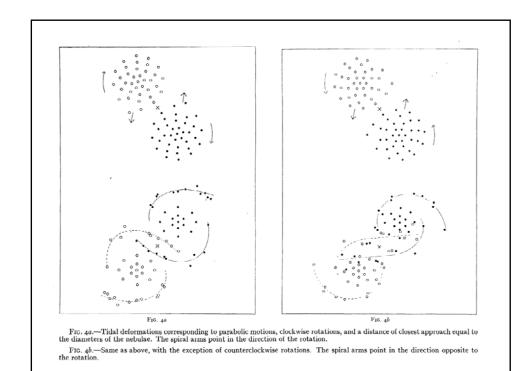
ON THE CLUSTERING TENDENCIES AMONG THE NEBULAE

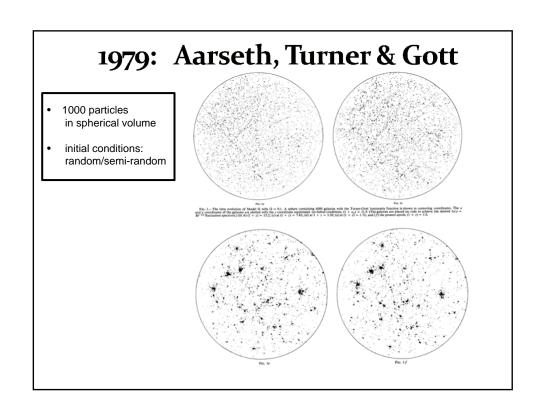
II. A STUDY OF ENCOUNTERS BETWEEN LABORATORY MODELS OF STELLAR SYSTEMS BY A NEW INTEGRATION PROCEDURE

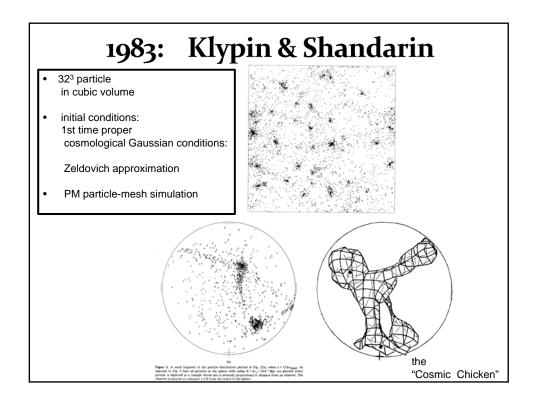
ERIK HOLMBERG

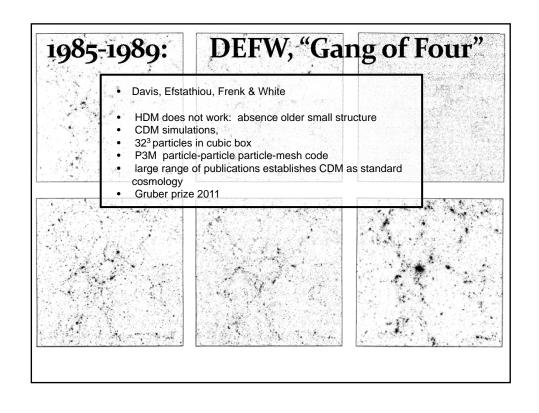
ABSTRACT

In a previous paper¹ the writer discussed the possibility of explaining the observed clustering effects among extragalactic nebulae as a result of captures. The present investigation deals with the important problem of whether the loss of energy resulting from the tidal disturbances at a close encounter between two nebulae is large enough to effect a capture. The tidal deformations of two models of stellar systems, passing each other at a small distance, are studied by reconstructing, piece by piece, the orbits described by the individual mass elements. The difficulty of integrating the total gravitational force acting upon a certain element at a certain point of time is solved by replacing gravitation by light. The mass elements are represented by light-bulbs, the candle power being proportional to mass, and the total light is measured by a photocell (Fig. 1). The nebulae are assumed to have a flattened shape, and each is represented by 37 light-bulbs. It is found that the tidal deformations cause an increase in the attaction between the two objects, the increase reaching its maximum value when the nebulae are separating, i.e., after the passage. The resulting loss of energy (Fig. 6) is comparatively large and may, in favorable cases, effect a capture. The spiral arms developing during the encounter (Figs. 4) represent an interesting by-product of the investigation. The direction of the arms depends on the direction of rotation of the nebulae with respect to the direction of their space motions.



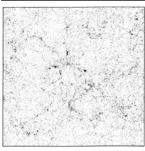






1985-1989: DEFW, "Gang of Four"

- Davis, Efstathiou, Frenk & White
- HDM does not work: absence older small structure
- · CDM simulations,
- 32³ particles in cubic box
- P3M particle-particle particle-mesh code
- large range of publications establishes CDM as standard cosmology
- Gruber prize 2011



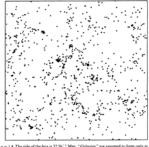
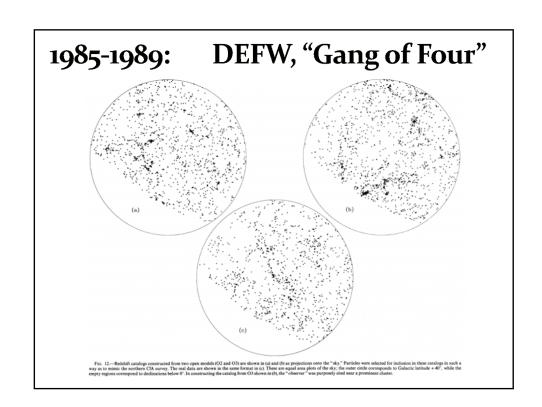
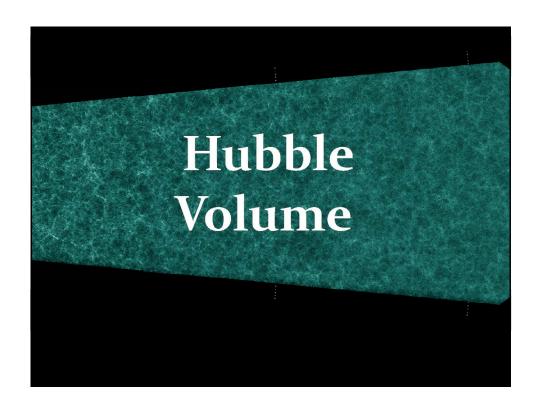
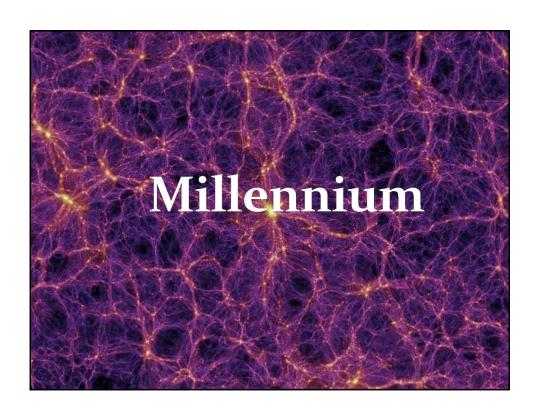
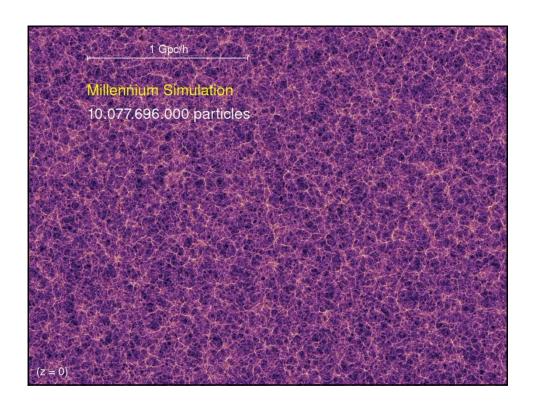


Fig. 16.—The projected distribution of all particles (left) and of the "galaxies" (right) in EdS1 at a = 1.4. The side of the box is 32.5k⁻¹ Mpc. "Galaxies" are assumed to form only a





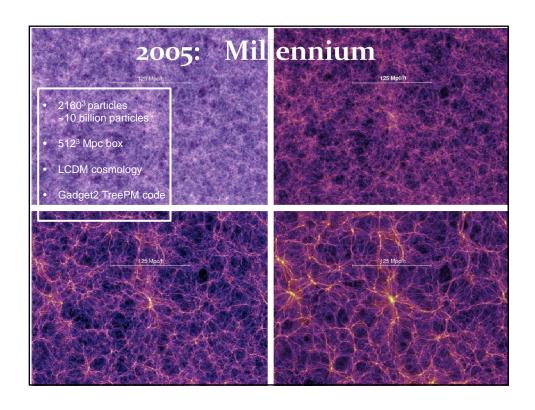


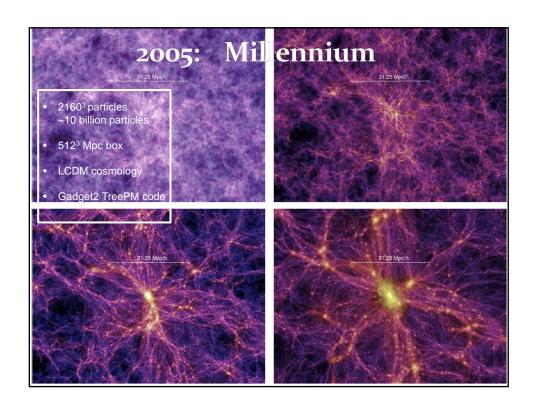


Millennium Simulation

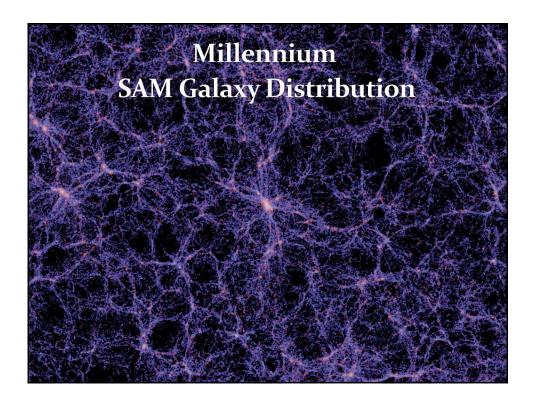
- Run: 2005
- Virgo consortium: UK-Germany centered European consortium
- 2005-2014: 650 publications based on Millennium
- Nbody simulation, TreePM (Gadget2)
- LCDM cosmology
- 2160³ particles ~ 10 x 10¹⁰ particles
- Volume: cubic region 500h-1 Mpc
- Resolution: 5h-1 kpc
- Dynamic range: 105 per dimension
- Data: 25 Terabyte
- Galaxy modelling by semi-analytical modelling
- 2x107 galaxies with mass > LMC
- Public Database:

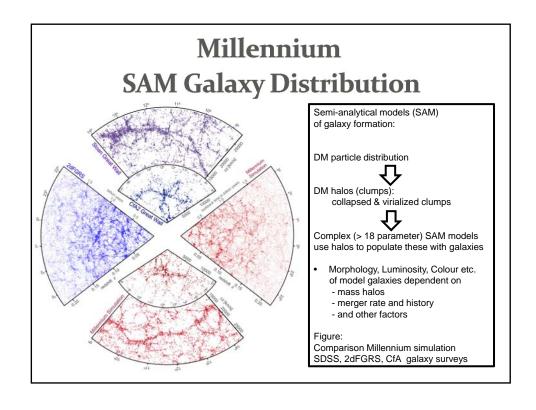
VO-oriented and SQL-queryable database (G. Lemson)



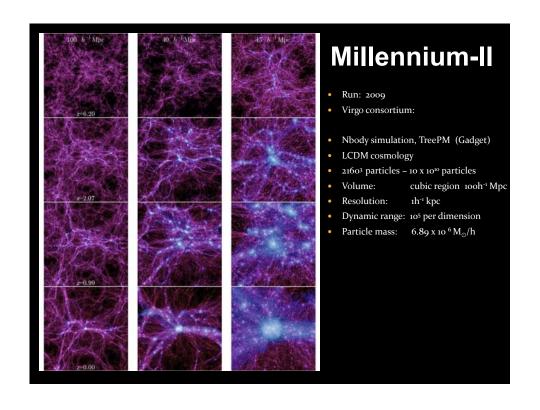


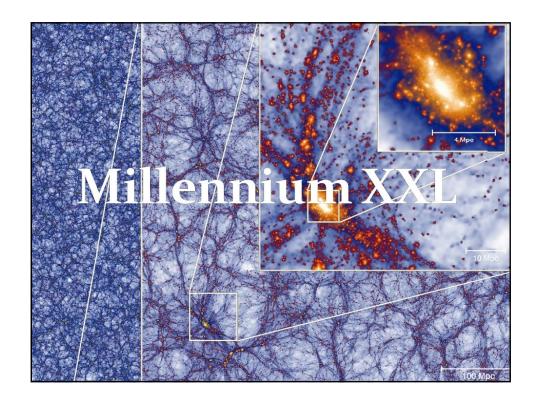












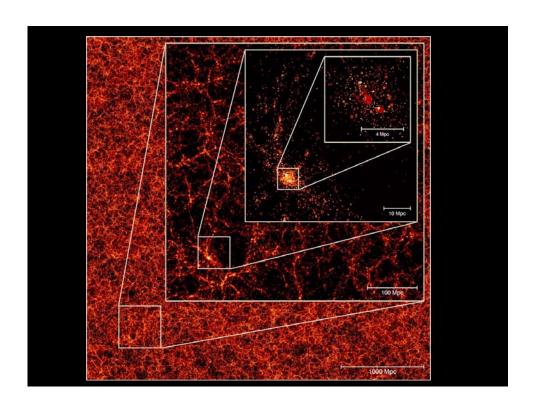
Millennium XXL Simulation

- Run: 2010
- Virgo consortium: UK-Germany centered European consortium
- First multi 100 billion particle simulation
- Nbody simulation, TreePM (Gadget2)
- LCDM cosmology
- 6720³ particles ~ 300 x 10¹⁰ particles
- Volume: cubic region 4.1 Gpc

216 volume Millennium

27000 volumes Millennium-II

- Run on JUROPA supercomputer, 12,000 cores, 300 years CPU time, 30 Terabyte RAM
- Data: 100 Terabyte
- Galaxy modelling by semi-analytical modelling
- 700 x 10⁶ galaxies at z=0



PM:

Particle-Mesh

The particle-mesh method

Poisson's equation can be solved in real-space by a convolution of the density field with a Green's function.

$$\Phi(\mathbf{x}) = \int g(\mathbf{x} - \mathbf{x}') \, \rho(\mathbf{x}) \, \mathrm{d}\mathbf{x}'$$

Example for vacuum boundaries:

$$\Phi(\mathbf{x}) = -G \int \frac{\rho(\mathbf{x})}{|\mathbf{x} - \mathbf{x}'|} d\mathbf{x}' \qquad g(\mathbf{x}) = -\frac{G}{|\mathbf{x}|}$$

In Fourier-space, the convolution becomes a simple multiplication!

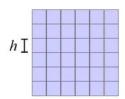
$$\hat{\Phi}(\mathbf{k}) = \hat{g}(\mathbf{k}) \cdot \hat{
ho}(\mathbf{k})$$

- Solve the potential in these steps:
 - (1) FFT forward of the density field (2) Multiplication with the Green's function
 - (3) FFT backwards to obtain potential

The four steps of the PM algorithm

- (a) Density assignment
- (b) Computation of the potential
- (c) Determination of the force field(d) Assignment of forces to particles

Density assignment



 $\left\{ \mathbf{x}_{m}
ight\} egin{array}{l} \mathsf{set} \ \mathsf{of} \ \mathsf{discrete} \ \mathsf{mesh} \ \mathsf{centres} \end{array}$

Give particles a "shape" S(x). Then to each mesh cell, we assign the fraction of mass that falls into this cell. The overlap for a cell is given by:

$$W(\mathbf{x_m} - \mathbf{x}_i) = \int_{\mathbf{x_m} - \frac{h}{2}}^{\mathbf{x_m} + \frac{h}{2}} S(\mathbf{x}' - \mathbf{x}_i) \, d\mathbf{x}' = \int \Pi\left(\frac{\mathbf{x}' - \mathbf{x_m}}{h}\right) S(\mathbf{x}' - \mathbf{x}_i) \, d\mathbf{x}'$$

The assignment function is hence the convolution:

$$W(\mathbf{x}) = \Pi\left(rac{\mathbf{x}}{h}
ight) \star S(\mathbf{x}) \qquad ext{where} \qquad \Pi(x) = \left\{egin{array}{ll} 1 & ext{for } |x| \leq rac{1}{2} \\ 0 & ext{otherwise} \end{array}
ight.$$

The density on the mesh is then a sum over the contributions of each particle as given by the assignment function:

$$ho(\mathbf{x_m}) = rac{1}{h^3} \sum_{i=1}^N m_i \, W(\mathbf{x_i} - \mathbf{x_m})$$

Commenly used particle shape functions and assignment schemes

Name	Shape function S(x)	# of cells involved	Properties of force
NGP Nearest grid point	• $\delta(\mathbf{x})$	$1^3 = 1$	piecewise constant in cells
CIC Clouds in cells	$\frac{1}{h^3} \Pi\left(\frac{\mathbf{x}}{h}\right) \star \delta(\mathbf{x})$	$2^{3} = 8$	piecewise linear, continuous
TSC Triangular shaped clouds	$\frac{1}{h^3} \Pi\left(\frac{\mathbf{x}}{h}\right) \star \frac{1}{h^3} \Pi\left(\frac{\mathbf{x}}{h}\right)$	$3^3 = 27$	continuous first derivative

Note: For interpolation of the grid to obtain the forces, the same assignment function needs to be used to ensure momentum conservation. (In the CIC case, this is identical to tri-linear interpolation.)

Advantages and disadvantages of the PM-scheme

Pros: SPEED and simplicity

Cons:

- Spatial force resolution limited to mesh size.
- Force errors somewhat anisotropic on the scale of the cell size

serious problem:

cosmological simulations cluster strongly and have a very large dynamic range

cannot make the PM-mesh fine enough and resolve internal structure of halos as well as large cosmological scales

we need a method to increase the dynamic range available in the force calculation

P3M:

Particle-Particle Particle-Mesh

Particle-Particle PM schemes (P3M)

Idea: Supplement the PM force with a direct summation short-range force at the scale of the mesh cells. The particles in cells are linked together by a chaining list.

Offers much higher dynamic range, but becomes slow when clustering sets in.

In AP3M, mesh-refinements are placed on clustered regions



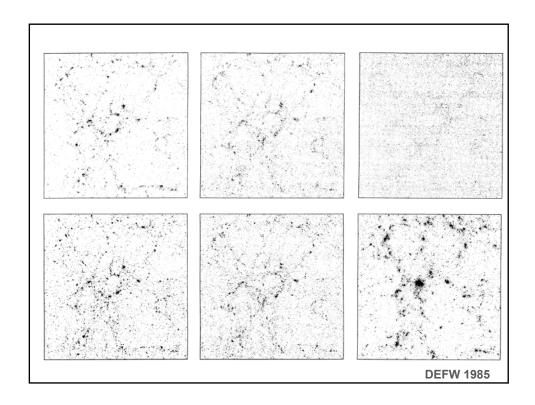
Can avoid clustering slow-down, but has higher complexity and ambiguities in mesh placement

Codes that use AP3M: HYDRA

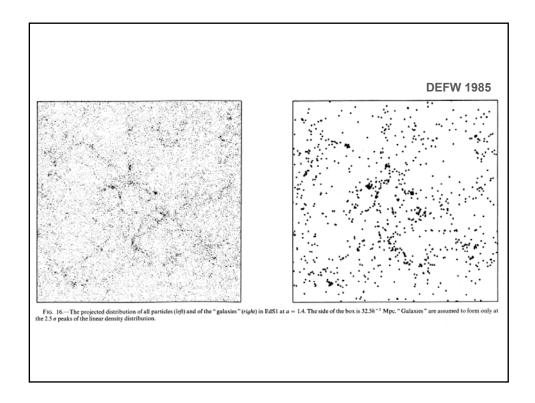
(Couchman)

DEFW:

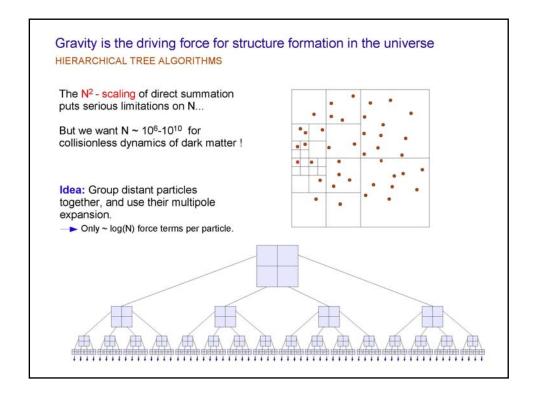
Davis -Efstathiou-Frenk-White 'the gang of four'

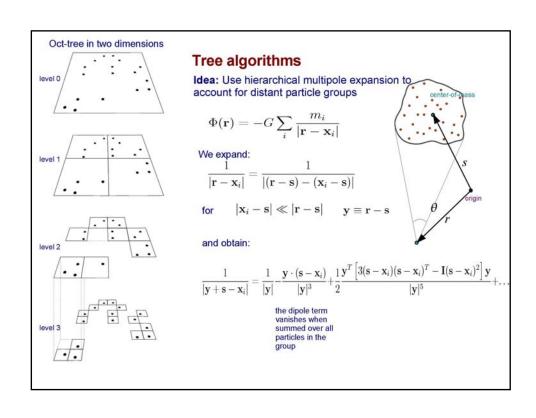






Tree Algorithms





The multipole moments are computed for each node of the tree

Monpole moment:

$$M = \sum_{i} m_i$$

Quadrupole tensor:

$$Q_{ij} = \sum_{k} m_k \left[3(\mathbf{x}_k - \mathbf{s})_i (\mathbf{x}_k - \mathbf{s})_j - \delta_{ij} (\mathbf{x}_k - \mathbf{s})^2 \right]$$

Resulting potential/force approximation:

$$\Phi(\mathbf{r}) = -G \left[\frac{M}{|\mathbf{y}|} \; + \; \frac{1}{2} \frac{\mathbf{y}^T \mathbf{Q} \, \mathbf{y}}{|\mathbf{y}|^5} \right]$$

For a single force evaluation, not N single-particle forces need to be computed, but **only of order** log(N) **multipoles**, depending on opening angle.

- The tree algorithm has no intrinsic restrictions for its dynamic range
- force accuracy can be conveniently adjusted to desired level the speed does depend only very weakly on clustering state
- geometrically flexible, allowing arbitrary geometries

TreePM

mixing Treecode with PM

Particularly at high redshift, it is expensive to obtain accurate forces with the tree-algorithm

THE TREE-PM FORCE SPLIT

Periodic peculiar potential

$$\nabla^2 \phi(\mathbf{x}) = 4\pi G[\rho(\mathbf{x}) - \overline{\rho}] = 4\pi G \sum_{\mathbf{n}} \sum_{i} m_i \left[\tilde{\delta}(\mathbf{x} - \mathbf{x}_i - \mathbf{n}L) - \frac{1}{L^3} \right]$$

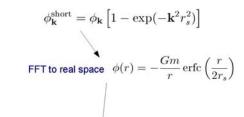
Idea: Split the potential (of a single particle) in Fourier space into a long-range and a short-range part, and compute them separately with PM and TREE algorithms, respectively.

Poisson equation in Fourier space:
$$\phi_{\bf k} = -\frac{4\pi G}{{\bf k}^2}\,\rho_{\bf k} \quad ({\bf k}\neq 0)$$

 $\phi_{\mathbf{k}}^{\text{long}} = \phi_{\mathbf{k}} \exp(-\mathbf{k}^2 r_s^2)$

- Solve with PM-method
 CIC mass assignment
 FFT

 - multiply with kernel FFT backwards
 - Compute force with 4-point finite difference operator
 - Interpolate forces to particle positions



Solve in real space with TREE

The maximum size of a TreePM simulation with Lean-GADGET-II is essentially memory bound

A HIGHLY MEMORY EFFICIENT VERSION OF GADGET-II

Particle Data

44 bytes / particle

Tree storage 40 bytes / particle

FFT workspace 24 bytes / mesh-cell

Not needed concurently!

Special code version Lean-GADGET-II needs: 84 bytes / particle

(Assuming 1.5 mesh-cells/particle)

Simulation Set-up:

Particle number:

 $2160^3 = 10.077.696.000 = \sim 10^{10}$ particles

Boxsize:

 $L = 500 h^{-1} \text{Mpc}$

Particle mass:

Size of FFT:

 $m_p = 8.6 \times 10^8 \, h^{-1} \, M_{\odot}$

Minimum memory requirement of simulation code

5 h -1 kpc Spatial resolution:

25603 = 16.777.216.000 = ~ 17 billion cells

~840 GByte

Compared to Hubble-Volume simulation:

> 2000 times better mass resolution

10 times larger particle number
13 better spatial resolution

Moving Mesh:

Arepo & TESS

A finite volume discretization of the Euler equations on a moving mesh can be readily defined

THE EULER EQUATIONS AS HYPERBOLIC SYSTEM OF CONSERVATION LAWS

Euler equations

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F} = 0$$

State vector

$$\mathbf{U} = \begin{pmatrix} \rho \\ \rho \mathbf{v} \\ \rho e \end{pmatrix}$$

Flux vector

$$\mathbf{F}(\mathbf{U}) = \begin{pmatrix} \rho \mathbf{v} \\ \rho \mathbf{v} \mathbf{v}^T + P \\ (\rho \epsilon + P) \mathbf{v} \end{pmatrix} \qquad \epsilon = u + \mathbf{v}^2$$

Equation of state: $P = (\gamma - 1)\rho u$

Discretization in terms of a number of finite volume cells:

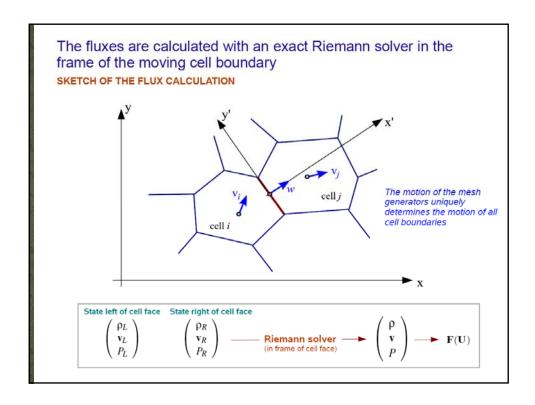
Cell averages

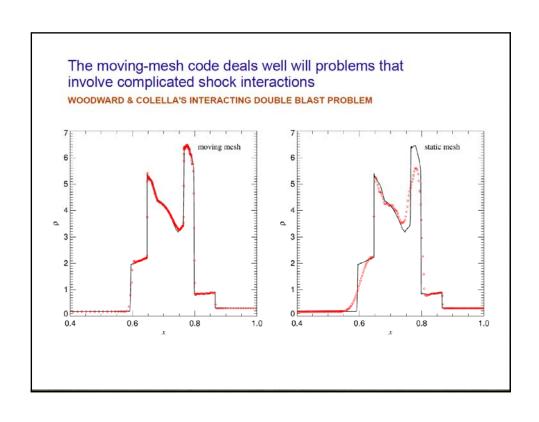
$$\mathbf{Q}_i = \left(\begin{array}{c} M_i \\ \mathbf{p}_i \\ E_i \end{array}\right) = \int_{V_i} \mathbf{U} \, \mathrm{d}V$$

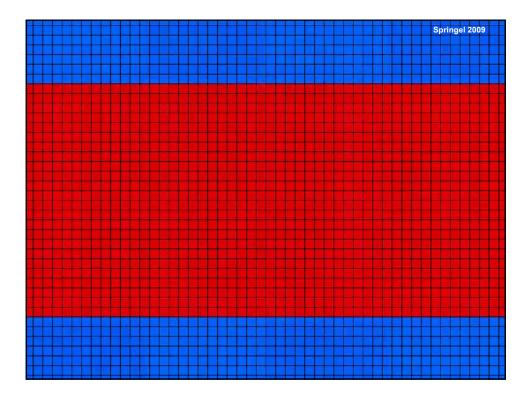
Evolution equatio

$$\frac{\mathrm{d}\mathbf{Q}_i}{\mathrm{d}t} = -\int_{\partial V_i} \left[\mathbf{F}(\mathbf{U}) - \mathbf{U}\mathbf{w}^T\right] \mathrm{d}\mathbf{n}$$

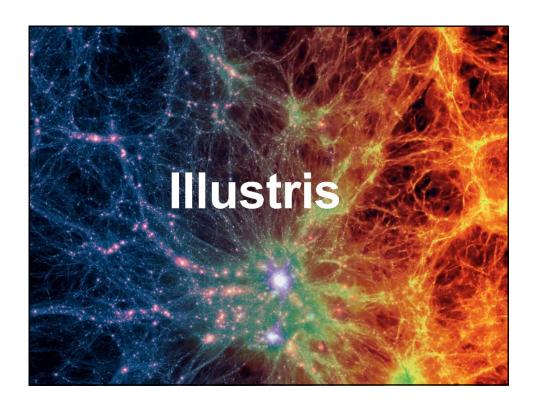
But how to compute the fluxes through cell surfaces?





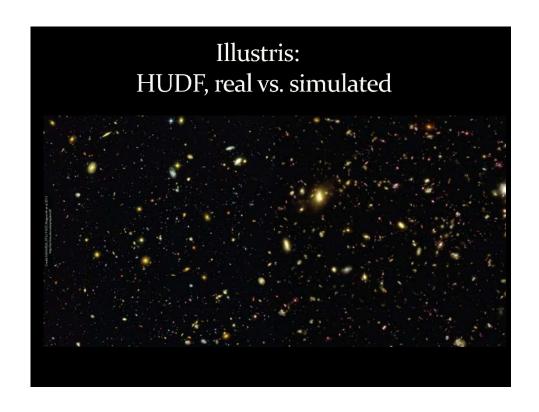


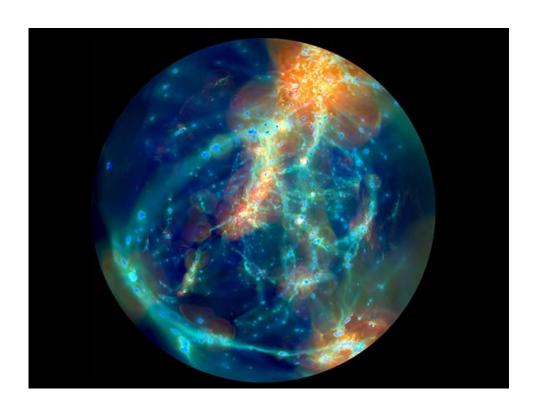


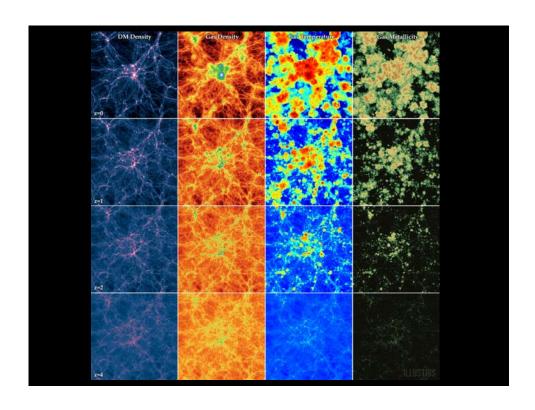


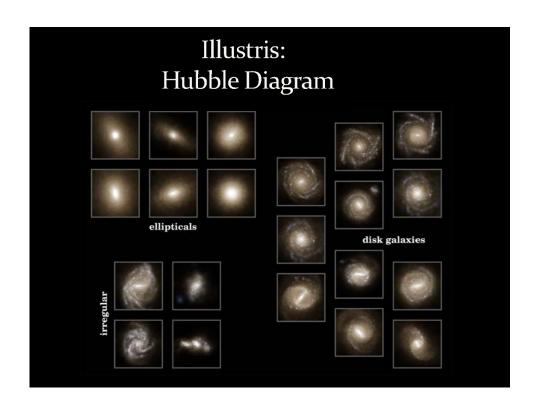
Illustris Simulation

- Run: 2013-2014
- First multi 100 billion particle simulation
- Arepo adaptive-grid (Voronoi) Nbody+hydro simulations
- LCDM cosmology
- 6720³ particles ~ 300 x 10¹⁰ particles
- Run on various supercomputers (France, Germany, USA),
 8192 cores, 19 million CPU hours, 25 Terabyte RAM
- Data: 230 Terabyte

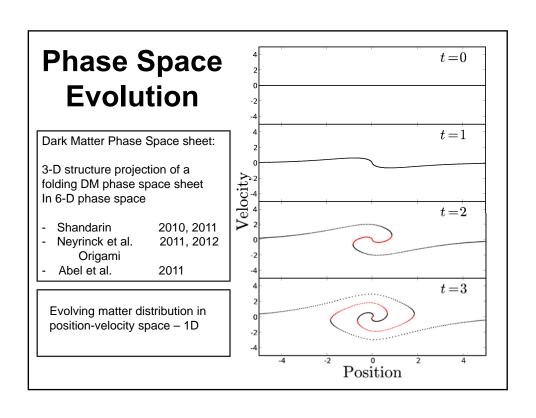








Phase-Space Dynamics



Phase Space Evolution

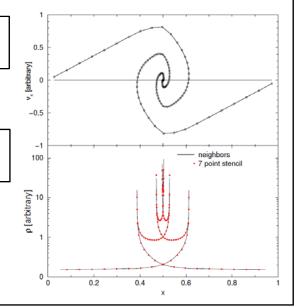
Phase space:

Velocity vs. Position



Density:

$$\rho(\vec{x},t) = \int f(\vec{x},\vec{v},t) d\vec{v}$$



Lagrangian-Eulerian Phase Space

To follow evolving phase-space of cosmic structure, it is sometimes insightful to consider a coordinate transformation of 6D phase-space:

Eulerian coordinates $\, \vec{x} \,$ and Eulerian coordinates $\, \vec{q} \,$ of a mass element:

$$f(\vec{x}, \vec{q})$$

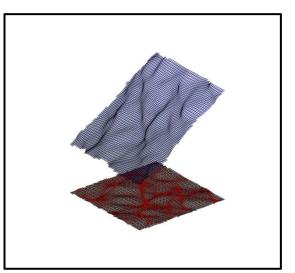
Note that in Zeldovich approximation, the velocity of a mass element is:

$$\vec{v}(\vec{q},t) = -a(t)D(t)f(\Omega) \ \vec{\nabla}\Phi(\vec{q})$$

Tessellation Deformation & Phase Space Projection

Translation towards Multi-D space:

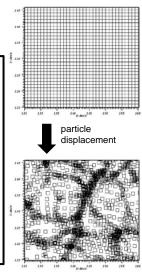
- Look at deformation of initial tessellation
- each tessellation cell represents matter cell
- evolution deforms cell
- once cells start to overlap, manifestation of different phase-space matter streams

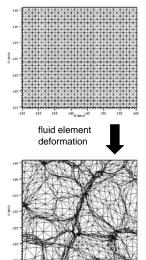


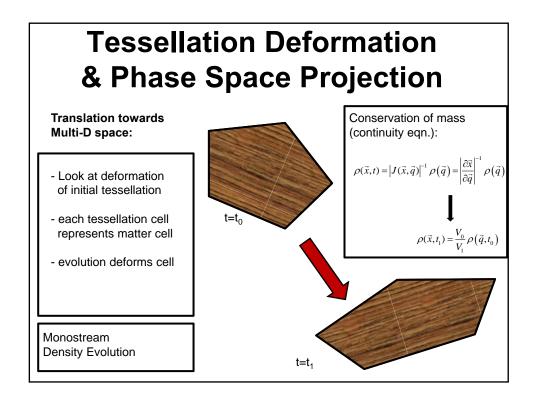
Tessellation Deformation & Phase Space Projection

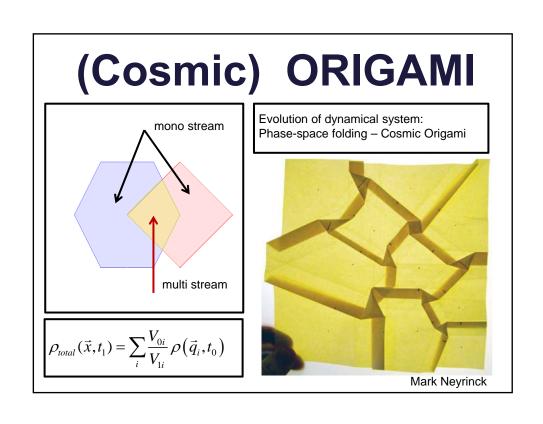
Translation towards Multi-D space:

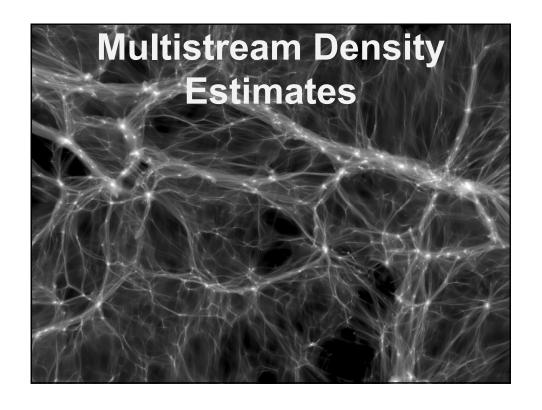
- Look at deformation of initial tessellation
- each tessellation cell represents matter cell
- evolution deforms cell
- once cells start to overlap, manifestation of different phase-space matter streams

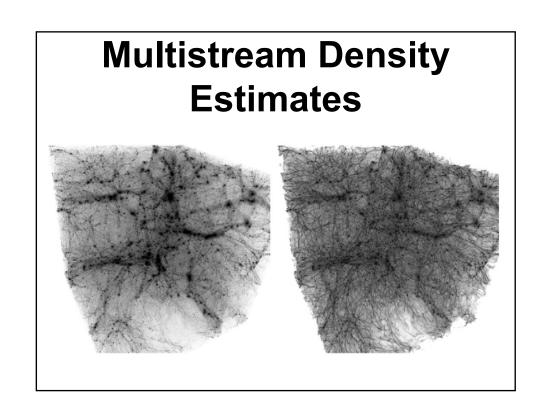


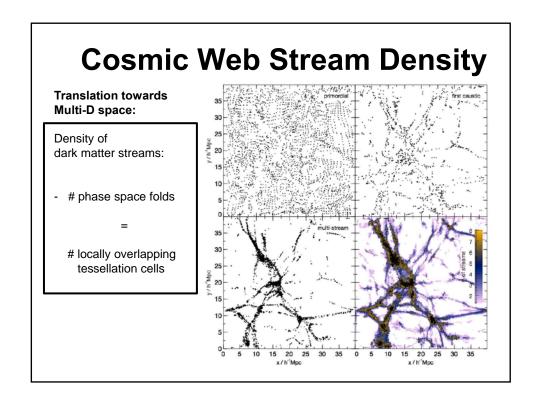












SPH

Smooth Particle Hydrodynamics

What is smoothed particle hydrodynamics? DIFFERENT METHODS TO DISCRETIZE A FLUID Eulerian Lagrangian discretize space discretize mass representation on a mesh representation by fluid elements (volume elements) (particles) principle advantage: principle advantage: high accuracy (shock capturing), low numerical viscosity resolutions adjusts automatically to the flow collapse

The baryons in the universe can be modelled as an ideal gas BASIC HYDRODYNAMICAL EQUATIONS

Euler equation:
$$\dfrac{\mathrm{d}\mathbf{v}}{\mathrm{d}t} = -\dfrac{\nabla P}{
ho} -
abla \Phi$$

Continuity equation:
$$\dfrac{\mathrm{d}
ho}{\mathrm{d} t} +
ho
abla \cdot \mathbf{v} = 0$$

First law of thermodynamics:
$$\frac{\mathrm{d}u}{\mathrm{d}t} = -\frac{P}{\rho}\nabla\cdot\mathbf{v} - \frac{\Lambda(u,\rho)}{\rho}$$

Equation of state of ideal monoatomic gas:
$$P = (\gamma - 1)\rho u \;, \qquad \gamma = 5/3$$

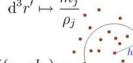
Kernel interpolation is used in smoothed particle hydrodynamics (SPH) to build continous fluid quantities from discrete tracer particles

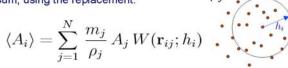
DENSITY ESTIMATION IN SPH BY MEANS OF ADAPTIVE KERNEL ESTIMATION

Kernel interpolant of an arbitrary function.

$$\langle A(\mathbf{r}) \rangle = \int W(\mathbf{r} - \mathbf{r}', h) \, A(\mathbf{r}') \, \mathrm{d}^3 r'$$

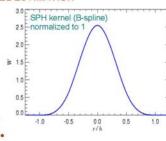
If the function is only known at a approximate the integral as a sum, using the replacement: $\mathrm{d}^3r'\mapsto\frac{m_j}{\rho_j}$





This leads to the SPH density estimate, for $A_i=
ho_i$

$$\rho_i = \sum_{j=1}^{N} m_j W(|\mathbf{r}_{ij}|, h_i)$$



This can be differentiated !

Kernel interpolants allow the construction of derivatives from a set of discrete tracer points

EXAMPLES FOR ESTIMATING THE VELOCITY DIVERGENCE

Smoothed estimate for the velocity field:

$$\langle \mathbf{v}_i
angle = \sum_i rac{m_j}{
ho_j} \, \mathbf{v}_j \, W(\mathbf{r}_i - \mathbf{r}_j)$$

Velocity divergence can now be readily estimated:

$$abla \cdot \mathbf{v} =
abla \cdot \langle \mathbf{v}_i
angle = \sum_j rac{m_j}{
ho_j} \, \mathbf{v}_j \,
abla_i W(\mathbf{r}_i - \mathbf{r}_j)$$

But alternative (and better) estimates are possible also:

Invoking the identity

$$ho
abla \cdot \mathbf{v} =
abla \cdot (
ho \mathbf{v}) - \mathbf{v} \cdot
abla
ho$$

one gets a "pair-wise" formula:

$$ho_i(
abla\cdot\mathbf{v})_i=\sum_j m_j(\mathbf{v}_j-\mathbf{v}_i)\,
abla_iW(\mathbf{r}_i-\mathbf{r}_j)$$

What is smoothed particle hydrodynamics?

BASIC EQUATIONS OF SMOOTHED PARTICLE HYDRODYNAMICS

Each particle carries either the energy or the entropy per unit mass as independent variable

Density estimate
$$\rho_i = \sum_{j=1}^N m_j W(|\mathbf{r}_{ij}|,h_i) \quad \longrightarrow \quad \text{Continuity equation automatically fulfilled.}$$

$$ightharpoonup P_i = (\gamma - 1)\rho_i u_i$$

 $+\Pi_{ij}$ Artificial viscosit

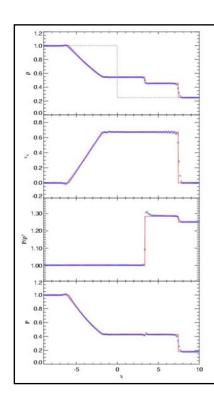
Euler equation

$$\frac{\mathrm{d}\mathbf{v}_i}{\mathrm{d}t} = -\sum_{j=1}^{N} m_j \left(\frac{P_i}{\rho_i^2} + \frac{P_j}{\rho_j^2} \right) \nabla_i \overline{W}_{ij}$$

First law of thermodynamics

$$\frac{\mathrm{d}u_i}{\mathrm{d}t} = \frac{1}{2} \sum_{i=1}^{N} m_j \left(\frac{P_i}{\rho_i^2} + \frac{P_j}{\rho_j^2} \right) \mathbf{v}_{ij} \cdot \nabla_i \overline{W}_{ij}$$

 $+\Pi_{ij}$



An artificial viscosity needs to be introduced to capture shocks

SHOCK TUBE PROBLEM AND VISCOSITY

viscous force:

$$\left. \frac{\mathrm{d} \mathbf{v}_i}{\mathrm{d} t} \right|_{\mathrm{visc}} = -\sum_{j=1}^N m_j \Pi_{ij} \nabla_i \overline{W}_{ij}$$

parameterization of the artificial viscosity:

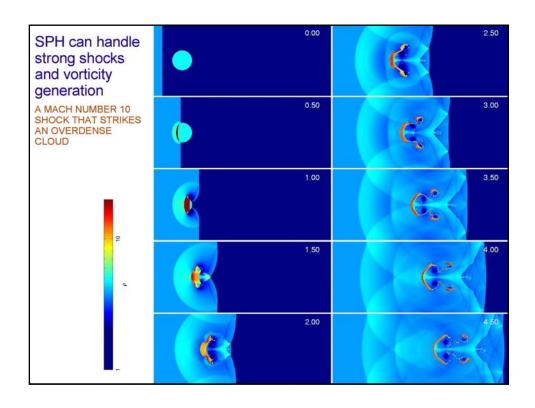
$$\Pi_{ij} = \left\{ egin{array}{ll} -rac{lpha}{2}rac{[c_i+c_j-3w_{ij}]w_{ij}}{
ho_{ij}} & ext{if } \mathbf{v}_{ij}\cdot\mathbf{r}_{ij} < 0 \\ 0 & ext{otherwise} \end{array}
ight.$$

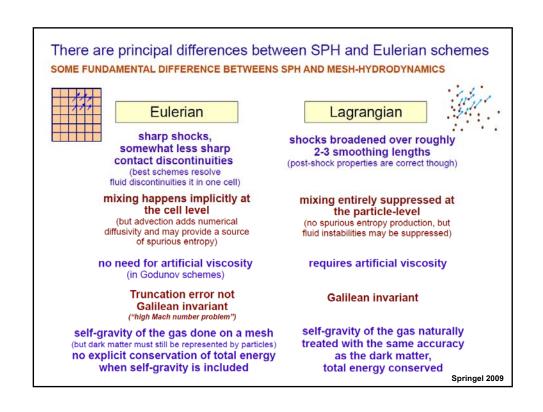
$$v_{ij}^{\text{sig}} = c_i + c_j - 3w_{ij},$$

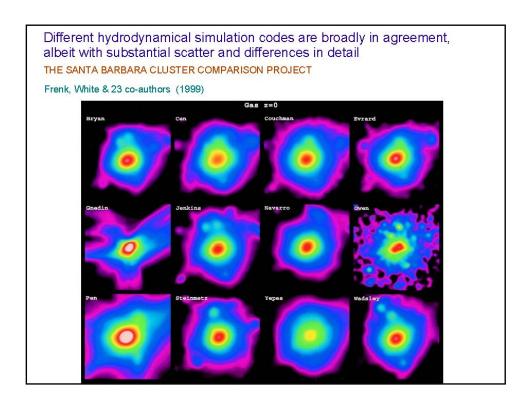
$$w_{ij} = \mathbf{v}_{ij} \cdot \mathbf{r}_{ij}/|\mathbf{r}_{ij}|$$

heat production rate:

$$\frac{\mathrm{d}u_i}{\mathrm{d}t} = \frac{1}{2} \sum_{j=1}^{N} m_j \Pi_{ij} \mathbf{v}_{ij} \cdot \nabla_i \overline{W}_{ij}$$



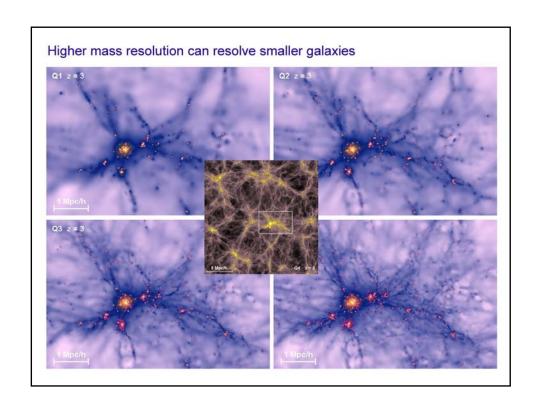


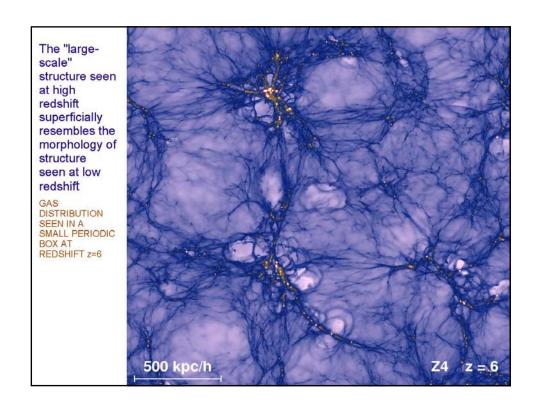


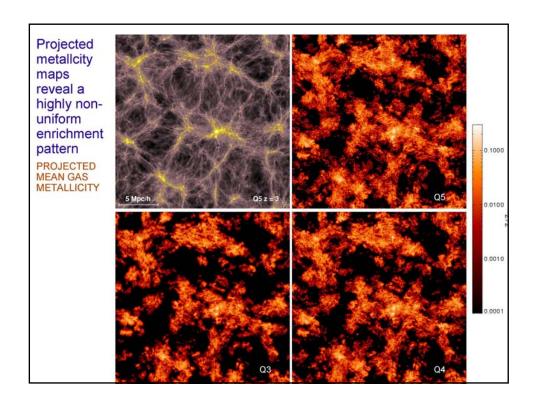
Nbody Simulations

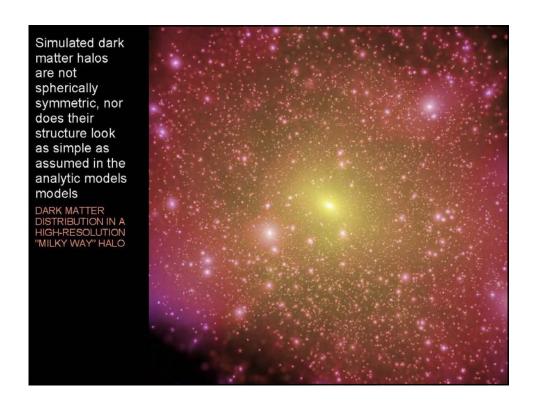
a select number of results

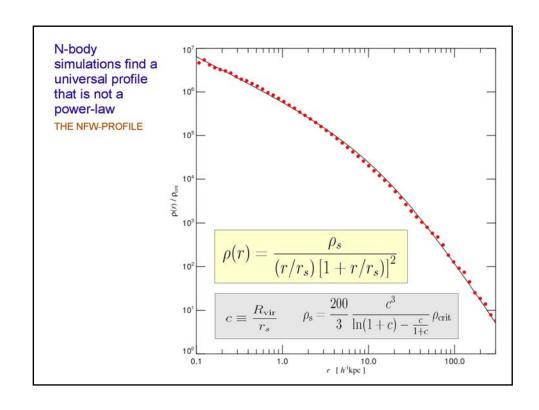
largely based on excellent Potsdam lectures on Nbody simulations (2006) by V. Springel

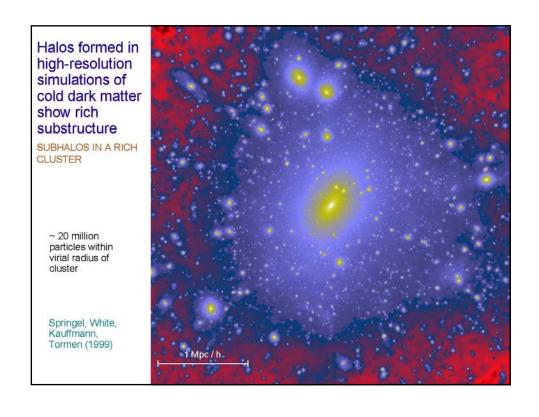


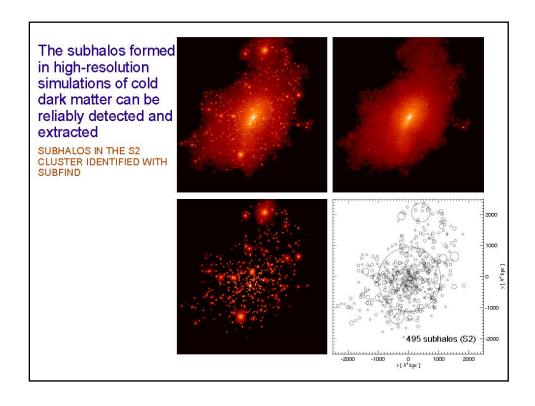












Semi-analytic Galaxy Formation & Subhalos

