

A large white optical telescope dome stands against a clear blue sky. The dome is open, revealing a green and white internal structure. A small figure of a person is visible at the base of the dome for scale. In the foreground, a white truck and some equipment are parked on a paved area. The text "VST" is overlaid in yellow in the top left corner, and the logo for the European Southern Observatory (ESO) is in the top right corner.

The logo for the Virtual Survey Telescope (VST) is located in the top right corner. It features a blue square with a white grid pattern, resembling a camera sensor or a grid of stars. Below the square, the text "Virtual Survey Telescope" is written in a blue, sans-serif font. At the bottom of the square, the acronym "VST" is written in a smaller blue font.

AstroWise paradigm	
"Classical" paradigm	Target processing - Awe
Forward chaining	Backward chaining
waterfall model	User hunts upstream
TIER architecture	
driven by input raw data	Driven by query of user
Process in pipeline workflow	Process in bits and pieces on the fly Backward chaining
Operators push data	User pulls data
Results in releases	Provide information system
Static archives – publish	Dynamic archives –publish Internet
Raw data - obsolete	Raw data is sacred

Astro-Wise VO Properties

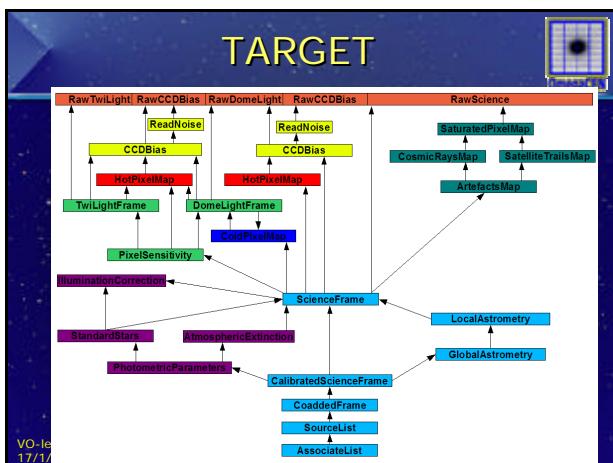
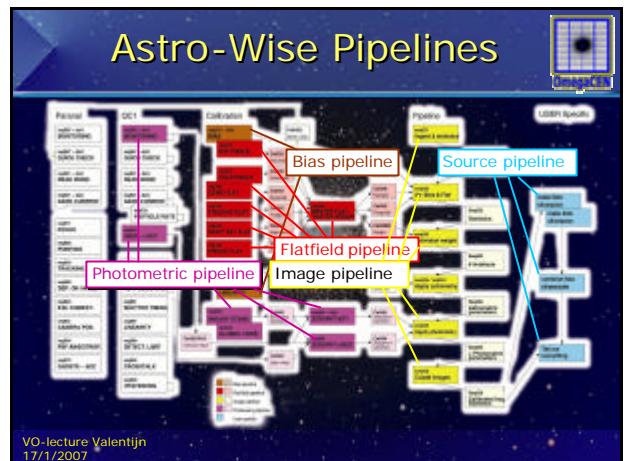
Benefits integrated dynamic db

- on-the fly re-processing
- 5LS: 5 Lines Script
- All bits are traced
- Administration for parallel processing
 - compute GRID SETI@home
- Global solutions –astrometry/photometry
- Build-in workflow
- Fully user tunable – own provided script
- Context: projects/surveys, instruments, mydb
- Publish directly in EURO-VO

time

- Calibrations vary in time due to
 - Physical changes
 - eg gain of detectors, atmosphere, flexure in telescope
 - Our insight in these changes, better modeling
 - Bugs in code and improved coding

VO-lecture Valentijn
17/1/2007



Target processing: ++ the make metaphor

```
awe> targethot=HotPixelMap.get(date='2003-02-14', chip='A5382')
```

The processing chain is

$$\text{ReadNoise} \leftarrow \text{Bias} \leftarrow \text{HotPixels}$$

```
> > class HotPixelMap(ProcessTarget):
> > > def self.make():
> > > class ProcessTarget():
> > > > def get(date, chip): # if not exist/up-to-date then make()
> > > > def exist(): # does the target exist?
> > > > def uptodate(): # is each dependency up to date?
```

Fully recursive

VO-lecture Valentijn
17/1/2007

Example 5LS

```
#Find ScienceFrames for a ccd named ccd53 and filter
Awe> q = (ReducedScienceFrame.chip.name == 'ccd') and
     (ReducedScienceFrame.filter == '841')
# From the query result, get the rms of the sky in image
Awe> x = [k.imstat.stdev for k in q]
# get the rms of the used Masterflat
Awe> y = [k.flat.imstat.stdev for k in q]
# Make a plot
Awe> pylab.scatter(x,y)
```

VO-lecture Valentijn
17/1/2007

Awe - GRIDS

- Collected in database – Oracle 10g and → federated servers using STREAMs
- distributed services → Virtual Survey Telescope
 - Code base, documentation, how-to's (CVS)
 - processing GRID
 - Storage GRID
 - Access to everything archive - SQL
 - Methods/services GRID
- facilitate research environment
 - Linux Python prompt
 - Bundled in web services www.astro-wise/portal

VO-lecture Valentijn
17/1/2007

