

Applied Signal Processing – 18/4/2007 13.00-16.00h

Please put your name and student number on all of your answer sheets. The final grade for this exam will be $\frac{9}{10.5}(\text{total number of points})+1$.

1. Find the z-transform of the following sequences. Wherever convenient, use the properties of the z-transform to make the solution easier:

(a) $x[n] = \left(\frac{1}{2}\right)^n \mu[-n]$ **(0.5)**

(b) $x[n] = \left(\frac{1}{3}\right)^n \mu[n] + 4^n \mu[-n-1]$ **(0.5)**

(c) $x[n] = n \left(\frac{1}{2}\right)^n \mu[n+1]$ **(0.5)**

2. Consider the discrete-time LTI system described by the following simple difference equation:

$$y[n] = x[n] - x[n-1]$$

PART I

- (a) Determine the impulse response of this system, $h[n]$, and plot $h[n]$.
- (b) Determine and write a closed-form expression for the DTFT, $H(e^{i\omega})$, of $h[n]$.
 $H(e^{i\omega})$ is the frequency response of the system.
- (c) Plot the magnitude $|H(e^{i\omega})|$ over the range $-\pi < \omega < \pi$
- (d) Plot the phase of $H(e^{i\omega})$ over $-\pi < \omega < \pi$ **((a)-(d) – 1.5 points)**

PART II

Given $x_a(t) = 3(1-|t|) \{ \mu(t+1) - \mu(t-1) \}$, where $\mu(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$.

Observe that $x_a(t)$ has a triangular shape of height 3 and a duration of 2 seconds centered at $t=0$.

Let $x[n] = x_a(nT_s)$, where $T_s = \frac{1}{3}$. This means that $x[n]$ is obtained by sampling $x_a(t)$ at the rate of 3 samples per second.

(e) Plot $x[n]$

(f) Determine and write a closed-form expression for the DTFT, $X(e^{i\omega})$, of $x[n]$

(g) Plot the magnitude $|X(e^{i\omega})|$ over $-\pi < \omega < \pi$ **((e)-(g) – 2 points)**

PART III

(h) Determine and plot the output signal $y[n]$ when the sampled signal $x[n]$ is input to the system $y[n] = x[n] - x[n-1]$

(i) Determine and write a closed-form expression for the DTFT, $Y(e^{i\omega})$, of $y[n]$

(j) Plot the magnitude $|Y(e^{i\omega})|$ over $-\pi < \omega < \pi$

(k) Determine the numerical value of $\sum_{n=-\infty}^{n=\infty} y^2[n]$. **((h)-(k) – 1.5 points)**

3. Consider the discrete-time LTI system defined by the transfer function

$$H(z) = \frac{20 - 24z^{-1} + 20z^{-2}}{(2 - z^{-1})(2 + 2z^{-1} + z^{-2})}$$

(a) Draw the pole-zero diagram of $H(z)$. **(0.5)**

(b) Given that the impulse response $h[n]$ of this system is causal, what is the Region of Convergence? **(0.5)**

(c) Draw a block diagram which implements this transfer function in cascade form, using 1st and 2nd order sections. **(1)**

4. Given the second orderband stop filter with transfer function

$$H_{BS}(z) = \frac{\kappa(1 - 2\beta z^{-1} + z^{-2})}{1 - \beta(1 + \alpha)z^{-1} + \alpha z^{-2}}$$

where α , β and γ are real constants, with $|\alpha| < 1$, $|\beta| < 1$

(a) Determine α and β so that filter has a notch at $\omega_0 = 0.3\pi$ and a band width of 0.3π . **(1)**

(b) What is the quality factor of the filter? **(0.5)**

(c) Draw the magnitude response of $H_{BS}(z)$ **(0.5)**